CIRCULAR CUPS WITH SELF-LOCKING SUPPORT

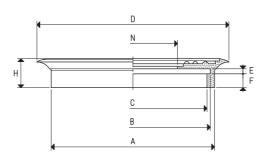
These cups represent a true mobile clamping system. They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

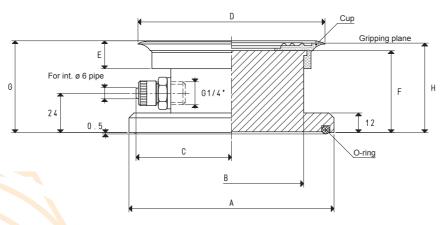




SPARE CUPS

Art.	Force	Α	В	С	D	E	F	Н	N	Weight
AIL.	Kg	Ø	Ø	Ø	Ø				Ø	g
01 85 15 *	14.18	68	63	59	85	3	7	17	27	29.7
01 110 10 *	23.74	96	91	87	114	3	8	17	54	44.3
01 150 10 *	45.00	133	125	118	154	4	11	23	64	112.0

 $^{^{\}star} \ Complete \ the \ code \ by \ indicating \ the \ compound: \ A= \ oil-resistant \ rubber; \ N= \ natural \ para \ rubber; \ S= \ silicon$



CUPS WITH SELF-LOCKING SUPPORT

Art.		Force	Α	В	С	D	Е	F	G	Н	Cup	0-ring	Weight
Aiti		Kg	Ø	Ø		Ø					Art.	Art.	Kg
16 85 15	*	14.5	98	60	41	85	17	49.0	56.0	54.5	01 85 15	00 16 06	0.542
16 110 1 <mark>0</mark>) *	24.0	125	88	58	114	17	50.0	56.0	54.5	01 110 10	00 16 07	1.056
16 150 10) *	45.0	165	120	76	154	23	49.5	57.5	54.5	01 150 10	00 16 08	1.858

^{*} Compl<mark>ete the co</mark>de by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

RECTANGULAR CUPS WITH SELF-LOCKING SUPPORT

These cups represent a true mobile clamping system.

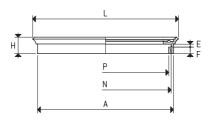
They are composed of:

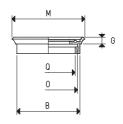
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.
- A standard rectangular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
 Two quick couplings for vacuum connection.
 The detection of vacuum, for gripping and releasing the

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.



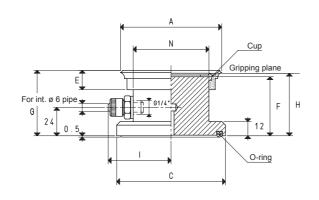


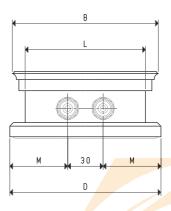


SPARE CUPS

SPARE C	,UF3													
Art.	Force	Α	В	Е	F	G	Н	L	M	N	0	Р	Q	Weight
	Kg													g
01 40 75 *	6.7	64	29	3	7.5	6.5	16.0	75	40	59	24	54	19	15.6
01 120 90 *	24.0	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2

 $^{^{\}star} \ \text{Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon$





CUPS WITH SELF-LOCKING SUPPORT

COFS W	IIII OLLI.	LOCKII	id 30Fi	ONI												
Art.	Force	Α	В	С	D	E	F	G	Н	I	L	М	N	Cup	0-ring	Weight
Aiu	Kg													Art.	Art.	Kg
16 40 75 *	6.7	41	76	48	83	16.0	51	56.5	54.5	30.5	55	26.5	20	01 40 75	00 16 09	0.260
16 120 90 *	24.0	90	120	98	128	17.5	50	57.0	54.5	56.0	102	49.0	70	01 120 90	00 16 10	1.166
16 150 75 *	25.0	75	150	83	144	16.5	50	57.0	54.5	48.0	130	57.0	55	01 150 75	<mark>00</mark> 16 10	1.177

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

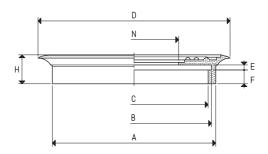
These cups represent a true mobile clamping system. They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

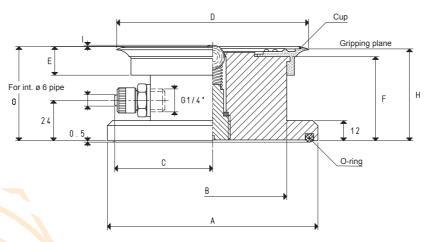




SPARE CUPS

Art.	Force	Α	В	С	D	Е	F	Н	N	Weight
AI L	Kg	Ø	Ø	Ø	Ø				Ø	g
01 85 15 *	14.18	68	63	59	85	3	7	17	27	29.7
01 110 10 *	23.74	96	91	87	114	3	8	17	54	44.3
01 150 10 *	45.00	133	125	118	154	4	11	23	64	112.0

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon



Art.		Force	Α	В	С	D	E	F	G	Н	I	Cup	0-ring	Weight
Aiti		Kg	Ø	Ø		Ø						Art.	Art.	Kg
18 85 1	5 *	14.5	98	60	41	85	17	49.0	56.0	54.5	1	01 85 15	00 16 06	0.580
18 110	10 *	24.0	125	88	58	114	17	50.0	56.0	54.5	1	01 110 10	00 16 07	1.106
18 150	10 *	45.0	165	120	76	154	23	49.5	57.5	54.5	1	01 150 10	00 16 08	1.926

^{*} Compl<mark>ete the c</mark>ode by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

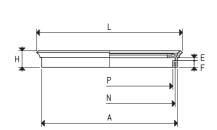
RECTANGULAR CUPS WITH BALL VALVE AND SELF-LOCKING SUPPORT

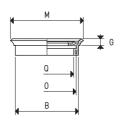
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- A standard rectangular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
 - A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
 - Two quick couplings for vacuum connection. The detection of vacuum. for gripping and releasing the

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

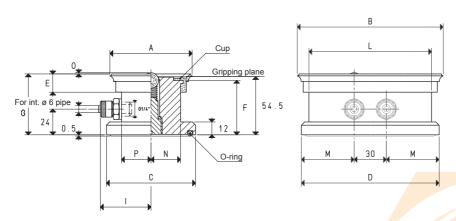




SPARE CUPS

01711111	,0.0													
Art.	Force	Α	В	Е	F	G	Н	L	М	N	0	Р	Q	Weight
Aiti	Kg													g
01 40 75 *	6.7	64	29	3	7.5	6.5	16.0	75	40	59	24	54	19	15.6
01 120 90 *	24.0	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2

 $^{^{\}star} \ Complete \ the \ code \ by \ indicating \ the \ compound: \ A= \ oil-resistant \ rubber; \ N= \ natural \ para \ rubber; \ S= \ silicon$



0013 1	VIIII DAL	L VALV	LAND	OLLI -L	-001/11/1	u sor r	OITI										
Art.	Force	Α	В	С	D	E	F	G	I	L	M	N	0	Р	Cup	0-ring	Weight
	Kg														Art.	Art.	Kg
18 40 75 *	6.7	41	76	48	83	16.0	51	56.5	41.5	55	26.5	15.0	2	21.0	01 40 75	<mark>0</mark> 0 16 09	0.352
18 120 90 *	24.0	90	120	98	128	17.5	50	57.0	56.0	102	49.0	35.0	1	35.0	01 120 90	<mark>0</mark> 0 16 10	1.224
18 150 75 *	25.0	75	150	83	144	16.5	50	57.0	48.0	130	57.0	27.5	1	27.5	01 150 75	<mark>0</mark> 0 16 10	1.194

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

These cups represent a true mobile clamping system.

They are composed of:

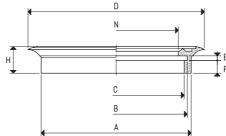
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- Two quick couplings for vacuum connection.

The gripping plane of these cups is covered with a special non-slip plastic coating, which is particularly suited for clamping glass and smooth marble. The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

Note: Available with support for mechanical fixing with code 28, instead of 18.

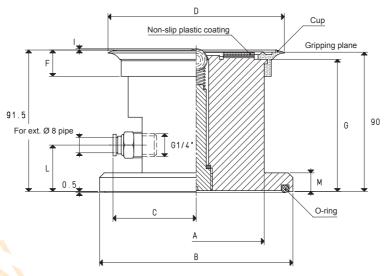




SPARE CUPS

017111	0010									
Art.	Force	Α	В	С	D	Е	F	Н	N	Weight
Alti	Kg	Ø	Ø	Ø	Ø				Ø	g
01 85 15 M *	14.18	68	63	59	85	3	7	17	53	26.2
01 110 10 M	* 23.74	96	91	87	114	3	8	17	80	40.1
01 150 10 M	* 45.00	133	125	118	154	4	11	23	117	98.3
01 250 20 *	122.60	235	227	220	254	4	11	23	220	188.6

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond



Art.		Force	Α	В	С	D	F	G	1	L	M	Cup	0-ring	Weight
Aiti		Kg	Ø	Ø		Ø						Art.	Art.	Kg
18 85 1	5/90 MT *	14.18	60	98	42	85	17	85.0	1	30	12	01 85 15 M	00 16 06	0.880
18 110	1 <mark>0/90 MT</mark> *	23.74	88	125	51	114	17	85.5	1	30	12	01 110 10 M	00 16 07	1.704
18 150	1 <mark>0/90 MT</mark> *	45.00	120	165	68	154	23	85.0	1	30	12	01 150 10 M	00 16 08	3.158
18 250	2 <mark>0/90 MT</mark> *	122.60	223	270	121	254	23	85.0	1	33	15	01 250 20	00 18 09	10.322

^{*} Compl<mark>ete the co</mark>de by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond

RECTANGULAR CUPS WITH BALL VALVE AND SELF-LOCKING SUPPORT

These cups represent a true mobile clamping system.

They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.
- A standard rectangular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.

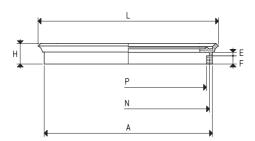
- Two quick couplings for vacuum connection.

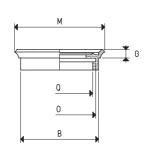
The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

Note: Available with support for mechanical fixing with code 28, instead of 18.



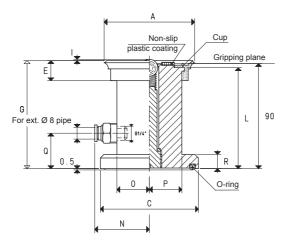


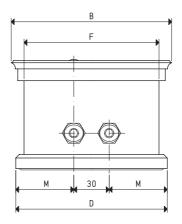


SPARE CUPS

0171112 00														
Art.	Force	Α	В	Е	F	G	Н	L	М	N	0	Р	Q	Weight
Aiu	Kg													g
01 40 75 *	6.7	64	29	3	7.5	6.5	16.0	75	40	59	24	54	19	15.6
01 120 90 *	24.0	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2
01 300 80 *	60.0	288	68	3	7.5	7.5	17.5	297	77	284	64	278	58	80.0
01 300 150 *	113.0	288	138	3	7.5	7.5	17.5	297	147	284	134	278	128	90.0

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond





Art.	Force	Α	В	С	D	Ε	F	G	- 1	L	M	N	0	Р	Q	R	Cup	0-ring	Weight
7	Kg																Art.	Art.	Kg
18 40 75/90 MT *	6.7	41	76	48	83	16.0	55	92.0	2	86.5	26.5	37.0	21.0	15.0	30	17	01 40 75	00 16 09	0.570
18 120 90/90 MT *	24.0	90	120	98	128	17.5	102	92.5	1	85.5	49.0	51.0	35.0	35.0	30	12	01 120 90	<mark>00</mark> 16 10	1.898
18 150 75/90 MT *	25.0	75	150	83	144	16.5	130	92.5	1	85.5	57.0	43.5	27.5	27.5	30	12	01 150 75	<mark>00</mark> 16 10	1.924
18 300 80/90 MT *	60.0	80	300	90	310	17.5	284	92.5	1	85.5	140.0	47.0	31.0	31.0	33	15	01 300 80	<mark>00</mark> 18 10	4.632
18 300 150/90 MT *	113.0	150	300	160	310	17.5	284	92.5	1	85.5	140.0	83.0	67.0	67.0	33	15	01 300 150	<mark>00</mark> 18 11	9.534

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond

These cups represent a true mobile clamping system. Their distinctive feature, with respect to the previous ones, is their exceptional height.

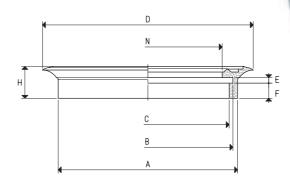
They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- Two quick couplings for vacuum connection.

The gripping plane of these cups is covered with a special non-slip plastic coating, which is particularly suited for clamping glass and smooth marble.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

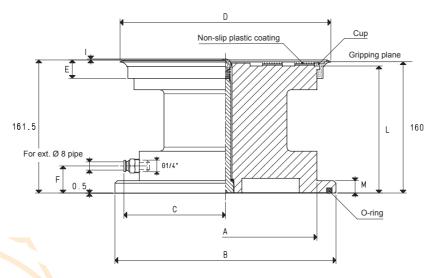
All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes. **Note:** Available with support for mechanical fixing with code 28, instead of 18.





SIAIL	0010									
Art.	Force	Α	В	С	D	E	F	Н	N	Weight
Aiti	Kg	Ø	Ø	Ø	Ø				Ø	g
01 110 10 M	* 23.74	96	91	87	114	3	8	17	80	40.1
01 150 10 M	* 45.00	133	125	118	154	4	11	23	117	98.3
01 250 20 *	122.60	235	227	220	254	4	11	23	220	188.6

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond



	Art.		Force	A	В	С	D	E	F	I	L	M	Cup	0-ring	Weight
	Aiti		Kg	Ø	Ø		Ø						art.	art.	Kg
18	B 110 1	1 <mark>0/160 M</mark> T *	24.0	88	125	51	114	17	30	1	155.5	12	01 110 10 M	00 16 07	2.986
18	3 150 1	1 <mark>0/160 M</mark> T *	45.0	120	165	68	154	23	30	1	155.5	12	01 150 10 M	00 16 08	5.042
18	B 250 2	2 <mark>0/160 M</mark> T *	122.6	223	270	121	254	23	33	1	155.5	15	01 250 20	00 18 09	12.634

^{*} Compl<mark>ete the co</mark>de by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond

RECTANGULAR CUPS WITH BALL VALVE AND HIGH SELF-LOCKING SUPPORT

These cups represent a true mobile clamping system. Their distinctive feature, with respect to the previous ones, is their exceptional height.

They are composed of:

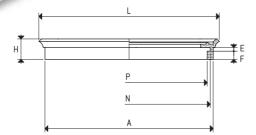
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.
- A standard rectangular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be

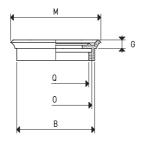
- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

Note: Available with support for mechanical fixing with code 28, instead of 18.

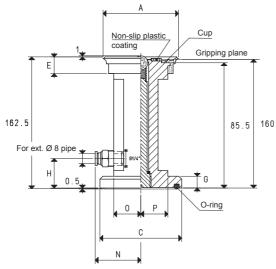


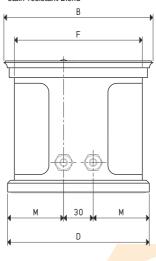


CDADE CLIDO

SPAIL OC	71 0													
Art.	Force	Α	В	Е	F	G	Н	L	M	N	0	Р	Q	Weight
	Kg													g
01 120 90 *	24.0	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2
01 300 80 *	60.0	288	68	3	7.5	7.5	17.5	297	77	284	64	278	58	80.0
01 300 150 *	113.0	288	138	3	7.5	7.5	17.5	297	147	284	134	278	128	90.0

* Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond





Art.	Force	Α	В	С	D	E	F	G	Н	М	N	0	Р	Cup	0-ring	Weight
ALL	Kg													Art.	Art.	Kg
18 120 90/160 MT *	24.0	90	120	98	128	17.5	102	12	30	49.0	51.0	35.0	35.0	01 120 90	00 16 10	3.450
18 150 75/160 MT *	25.0	75	150	83	144	16.5	130	12	30	57.0	43.5	27.5	27.5	01 150 75	<mark>00</mark> 16 10	3.262
18 300 80/160 MT *	60.0	80	300	90	310	17.5	284	15	33	140	47.0	31.0	31.0	01 300 80	<mark>00</mark> 18 10	7.906
18 300 150/160 MT *	113.0	150	300	160	310	17.5	284	15	33	140	83.0	67. <mark>0</mark>	67.0	01 300 150	00 18 11	13.110

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon; BA= stain-resistant Biond

Glass machinery manufacturers require increasingly accurate and safe clamping machines. This has led us to the creation of this series of cups.

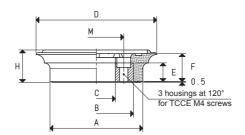
The specially designed shape of this cup guarantees a firm grip. The other main feature is the utmost precision in the height, whose nominal size has a tolerance of only five hundredths of millimetre.

They are composed of:

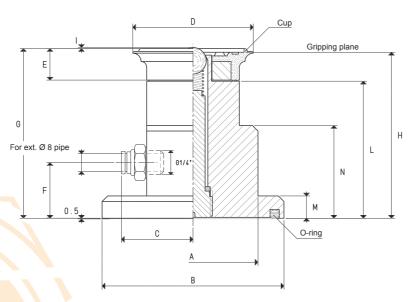
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- Two quick couplings for vacuum connection.

The gripping plane of these cups is covered with a special non-slip plastic coating, which is particularly suited for clamping glass and smooth marble. The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.



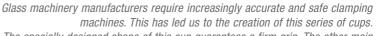


SFANE	CUF										
Art.	Force	Α	В	С	D	E	F	Н	M	Support	Weight
Art.	Kg	Ø	Ø	Ø	Ø				Ø	material	g
08 65 11 A	6.7	50	40	20.5	65	10	15	17.5	29.5	steel	90



Art.		Force	Α	В	C	D	Ε	F	G	Н	- 1	L	M	N	Cup	0-ring	Weight
		Kg	Ø	Ø		Ø									Art.	Art.	Kg
18 65 1	/90 A	6.7	70	98	45	6 <mark>5</mark>	17.5	30	92.5	90	1	75	12	50	08 65 11 A	00 16 06	1.090

RECTANGULAR CUPS WITH BALL VALVE AND SELF-LOCKING SUPPORT, FOR GLASS



The specially designed shape of this cup guarantees a firm grip. The other main feature is the utmost precision in the height, whose nominal size has a tolerance of only five hundredths of millimetre.

They are composed of:

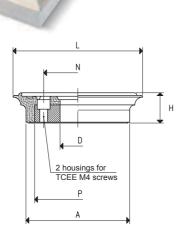
- A sturdy anodised aluminium support with a wide surface at the base limited by a seal whose purpose is to fix it to the bearing surface.

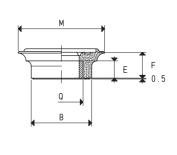
- A standard rectangular flat cup which is cold-assembled onto the upper part of the support for gripping the load.

- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.

- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

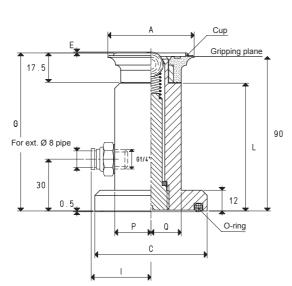


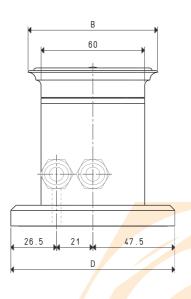


SPARE CUP

185075/90 500 N. 100

SE	ANE GU	7													
Art.		Force	Α	В	D	E	F	Н	L	M	N	Р	Q	Support	Weight
AI G		Kg			Ø									material	g
08 50 7	5 A	7.5	60	35	20.5	10	15	17.5	75	50	39.5	50	25	steel	92





CLID WITH BALL VALVE AND SELET OCKING SLIDDORT

CUP	VVIIHE	BALL	- VAL	VE AN	D SE	ELF-LO	CKING	SUPPOR	I								
Art.		F	orce		Α	В	С	D	Е	G	I	L	Р	Q	Cup	0-ring	Weight
Aiu			Kg												Art.	Art.	Kg
18 50 75/	90 A		7.5		50	75	65	95	1	92.5	41	75	21	17.5	08 50 75 A	00 16 06	0.762

Glass machinery manufacturers require increasingly accurate and safe clamping machines. This has led us to the creation of this series of cups.

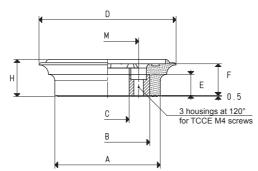
The specially designed shape of this cup guarantees a firm grip. The other main feature is the utmost precision in the height, whose nominal size has a tolerance of only five hundredths of millimetre.

They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- A release button that allows placing the support even with the vacuum inserted.
- Two quick couplings for vacuum connection.

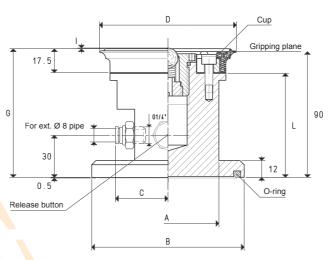
The gripping plane of these cups is covered with a special non-slip plastic coating, which is particularly suited for clamping glass and smooth marble. The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.





SPA	DE.	\cap	\Box
SPAI	RE I	\cup U	М

SPARE	CUP										
Art.	Force	Α	В	С	D	E	F	Н	M	Support	Weight
AI L	Kg	Ø	Ø	Ø	Ø				Ø	material	g
08 85 11 A	1 12	70	60	40.5	85	10	15	17.5	49.5	steel	92

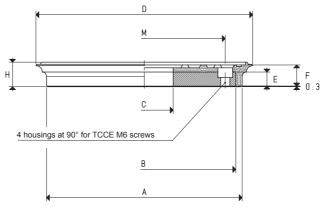


CUP WITH BALL VALVE AND SELF-LOCKING SUPPORT AND RELEASE BUTTON

Art.		Force	Α	В	С	D	G	I	L	Cup	0-ring	Weight
Alti		Kg	Ø	Ø	V	Ø				art.	art.	Kg
21 85 1	1/90 A	12.0	70	98	42	85	92.5	1	75	08 85 11 A	00 16 06	1.090

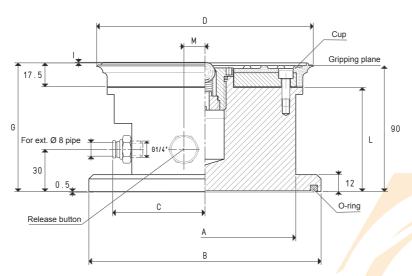
CIRCULAR CUPS WITH BALL VALVE, SELF-LOCKING SUPPORT AND RELEASE BUTTON, FOR GLASS





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SEAI	י שר	-U	_

Art.	Force	Α	В	С	D	E	F	Н	M	Support	Weight
AIG	Kg	Ø	Ø	Ø	Ø				Ø	material	Kg
08 150 11 A	42.7	139	130	41.0	150	10	15	17.5	115.0	steel	1.0



CUP WITH BALL VALVE AND SELF-LOCKING SUPPORT AND RELEASE BUTTON

Art.	Force	Α	В	С	D	G	I	L	M	Cup	0-ring	Weight	
Alu	Kg	Ø	Ø		Ø					Art.	Art.	Kg	
21 150 11/90 A	42.7	129	165	73	150	92.5	1	75	15	08 150 11 A	00 16 08	3.938	

CIRCULAR CUPS WITH BALL VALVE, **SELF-LOCKING SUPPORT AND RELEASE BUTTON**

These cups represent a true mobile clamping system.

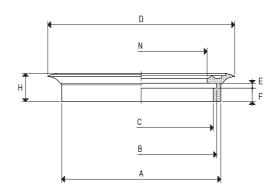
They are composed of:

- A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
- A standard circular flat cup which is cold-assembled onto the upper part of the support for gripping the load.
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.
- A release button that allows placing the support even with the vacuum inserted.
- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

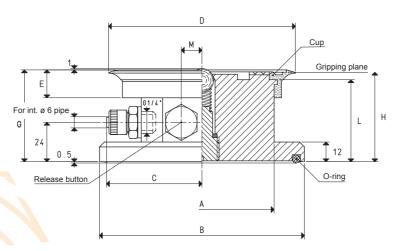




CDADE	CLIDE
SPARE	CUES

0171	IL 001 0									
Art.	Force	Α	В	С	D	E	F	Н	N	Weight
74.4	Kg	Ø	Ø	Ø	Ø				Ø	g
01 110 10	M * 23.74	96	91	87	114	3	8	17	80	40.1
01 150 10	M * 45.00	133	125	118	154	4	11	23	117	98.3

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon



CUPS WITH BALL VALVE, SELF-LOCKING SUPPORT AND RELEASE BUTTON

Art.		Force	Α	В	C	D	Е	G	Н	L	M	Cup	0-ring	Weight
Aiti		Kg	Ø	Ø		Ø						Art.	Art.	Kg
21 110	10 *	24	88	125	58	114	17	56.0	54.5	50.0	10	01 110 10 M	00 16 07	1.148
21 150 1	10 *	45	120	165	76	154	23	57.5	54.5	49.5	28	01 150 10 M	00 16 08	2.042

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

3D drawings available at www.vuototecnica.net

RECTANGULAR CUPS WITH BALL VALVE, SELF-LOCKING SUPPORT AND RELEASE BUTTON



These cups represent a true mobile clamping system.

They are composed of:

 A sturdy anodised aluminium support with a wide surface at the base limited by a seal, whose purpose is to fix it to the bearing surface.
 A standard rectangular flat cup which is cold-assembled onto the upper part

a standard rectangular that cup which is cold-assembled onto the upper part of the support for gripping the load.

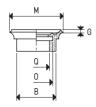
- A ball valve that opens up creating vacuum, only when activated by the load to be gripped.

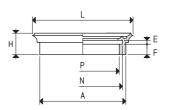
- A release button that allows placing the support even with the vacuum inserted.

- Two quick couplings for vacuum connection.

The detection of vacuum, for gripping and releasing the support, can be made via three-way vacuum valves or solenoid valves.

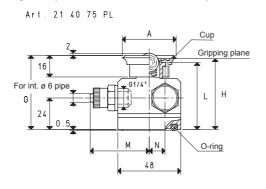
All cups with self-locking support of this and other ranges with the gripping plane at the same height can be used simultaneously, even if they are of different types or have different sizes.

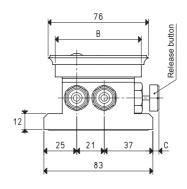


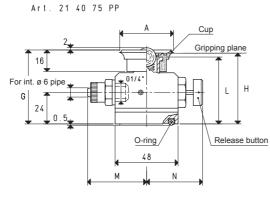


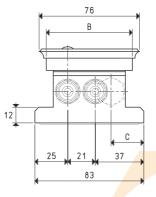
SPARE	: CUPS													
Art.	Force	Α	В	E	F	G	Н	L	M	N	0	Р	Q	Weight
	Kg													g
01 40 75 *	6.7	64	29	3	7.5	6.5	16.0	75	40	59	24	54	19	15.6

* Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon









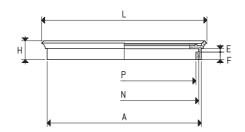
CUPS WITH BALL VALVE, SELF-LOCKING SUPPORT AND RELEASE BUTTON

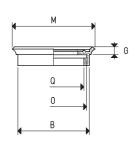
Ant	Force	Α	В	С	G	Н	L	М	N	Cup	0-ring	Weight
Art.	Kg									Art.	Art.	Kg
21 40 75 PL	6.7	41	55	7	56.5	54.5	51	45.5	12	01 40 75	00 16 09	0.460
21 40 75/84 PL *	6.7	41	55	7	86.5	84.0	81	45.5	12	01 40 75	00 16 09	0.702
21 40 75 PP *	6.7	41	55	25	56.5	54.5	51	45.5	45	01 40 75	00 16 09	0.460
21 40 75/ 84 PP *	6.7	41	55	25	86.5	84.0	81	45.5	45	01 40 75	00 16 09	0.702

^{*} Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon

RECTANGULAR CUPS WITH BALL VALVE, SELF-LOCKING SUPPORT AND RELEASE BUTTON



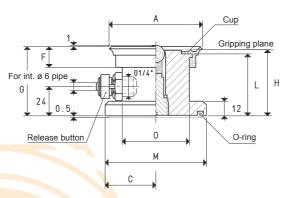


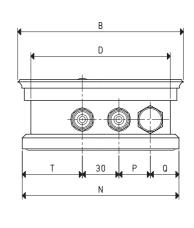


SPARE CUPS		

Art.	Force	Α	В	E	F	G	Н	L	M	N	0	Р	Q	Weight
	Kg													g
01 120 90 *	24.0	107	78	3	7.5	7.5	17.5	117	87	102	73	97	68	38.8
01 150 75 *	25.0	137	62	3	7.5	7.5	16.5	147	72	132	57	127	52	41.2

 $^{^\}star$ Complete the code by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon





CLIDE WITH DALL	WALVE CELL	E LOCKING SUDDODT	AND RELEASE BUTTON
COPS WITH BALL	VALVE, SELI	r-LUCKING SUPPORT	AND RELEASE BUILDIN

A		Force	Α	В	С	D	F	G	Н	L	M	N	0	Р	Q	T	Cup	0-ring	Weight
Art.		Kg															Art.	Art.	Kg
21 120	90 *	24	90	120	56	102	17.5	57.0	54.5	50	98	128	70	24	25	49	01 120 90	00 16 10	1.320
21 150	75 *	25	75	120	48	130	16.5	57.0	54.5	50	83	144	55	25	32	57	01 150 75	00 16 10	1.236
21 150	75/84 *	25	75	150	48	130	16.5	86.5	84.0	80	83	144	55	25	32	57	01 150 75	00 16 10	1.924

^{*} Compl<mark>ete the co</mark>de by indicating the compound: A= oil-resistant rubber; N= natural para rubber; S= silicon